

CE 3354 ENGINEERING HYDROLOGY

Lecture 6: Probability Estimation
Modeling

OUTLINE

- ▶ Probability estimation modeling – background
- ▶ Probability distributions
- ▶ Plotting positions

WHAT IS PROBABILITY ESTIMATION?

- ▶ Use of probability distributions to model or explain behavior in observed data.
- ▶ Once a distribution is selected, then the concept of risk (probability) can be explored for events (rainfalls, discharges, concentrations, etc.) of varying magnitudes.
- ▶ Two important “extremes” in engineering:
 - ▶ relatively uncommon events (floods, plant explosions, etc.)
 - ▶ very common events (routine discharges, etc.)

FREQUENCY ANALYSIS

- ▶ Frequency analysis relates the behavior of some variable over some recurring time intervals.
- ▶ The time interval is assumed to be large enough so that the concept of “frequency” makes sense.
 - ▶ “Long enough” is required for independence, that is the values of the variable are statistically independent, otherwise the variables are said to be serial (or auto-) correlated.
- ▶ If the time intervals are short, then dealing with a time-series; handled using different tools.

T-YEAR EVENTS

- ▶ The T-year event concept is a way of expressing the probability of observing an event of some specified magnitude or smaller (larger) in one sampling period (one year).
- ▶ Also called the Annual Recurrence Interval (ARI)
- ▶ The formal definition is: The T-year event is an event of magnitude (value) over a **long** time-averaging period, whose average arrival time between events of such magnitude is T-years.
- ▶ The Annual Exceedence Probability (AEP) is a related concept

$$X - \text{year ARI} = \frac{1 \text{ yr.}}{X \text{ yr.}} = 1 / X \text{ AEP}$$

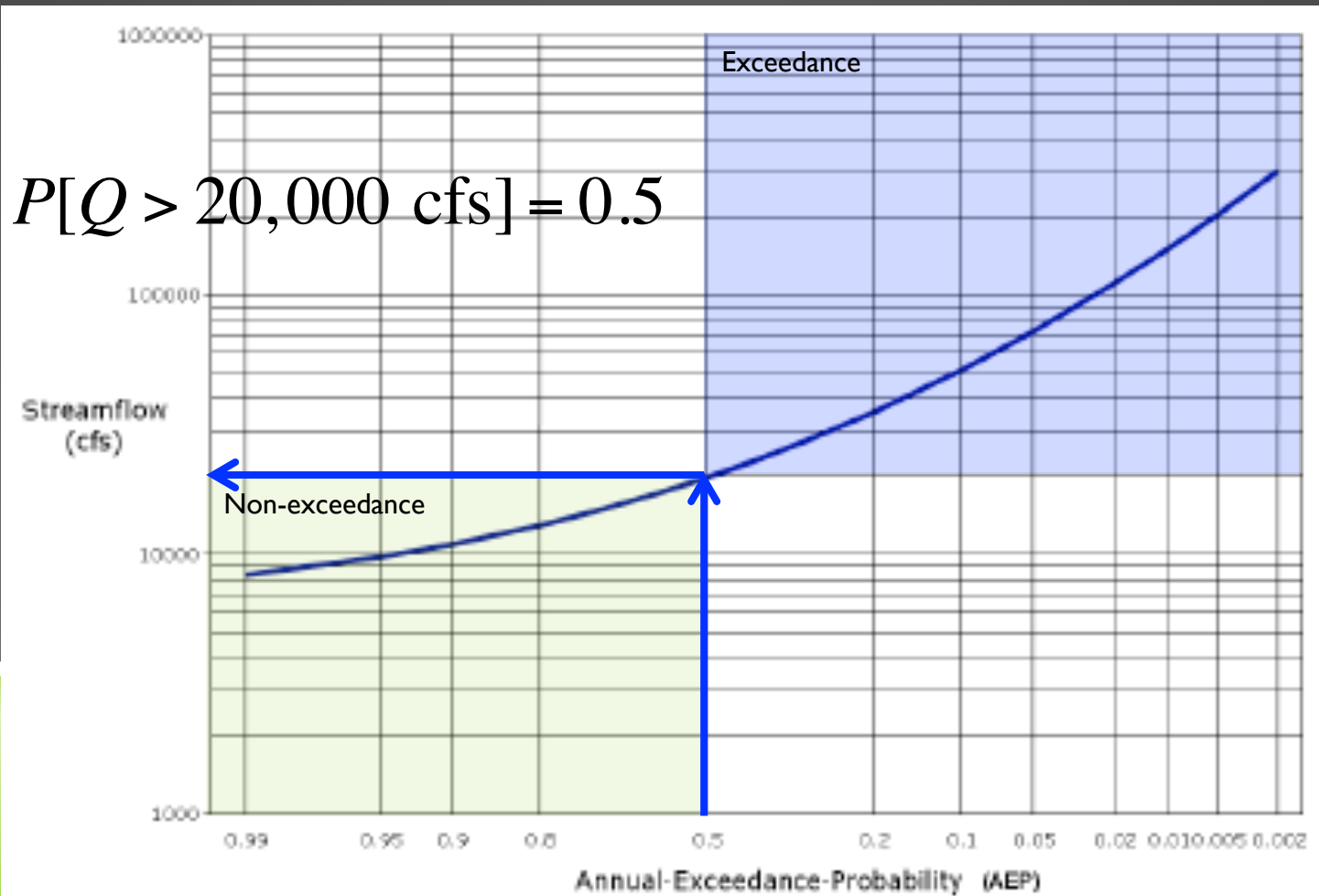
NOTATION

$$P[x > X] = y$$

- ▶ Most probability notations are similar to the above statement.
- ▶ We read them as “The probability that the random variable x will assume a value greater than X is equal to y ”

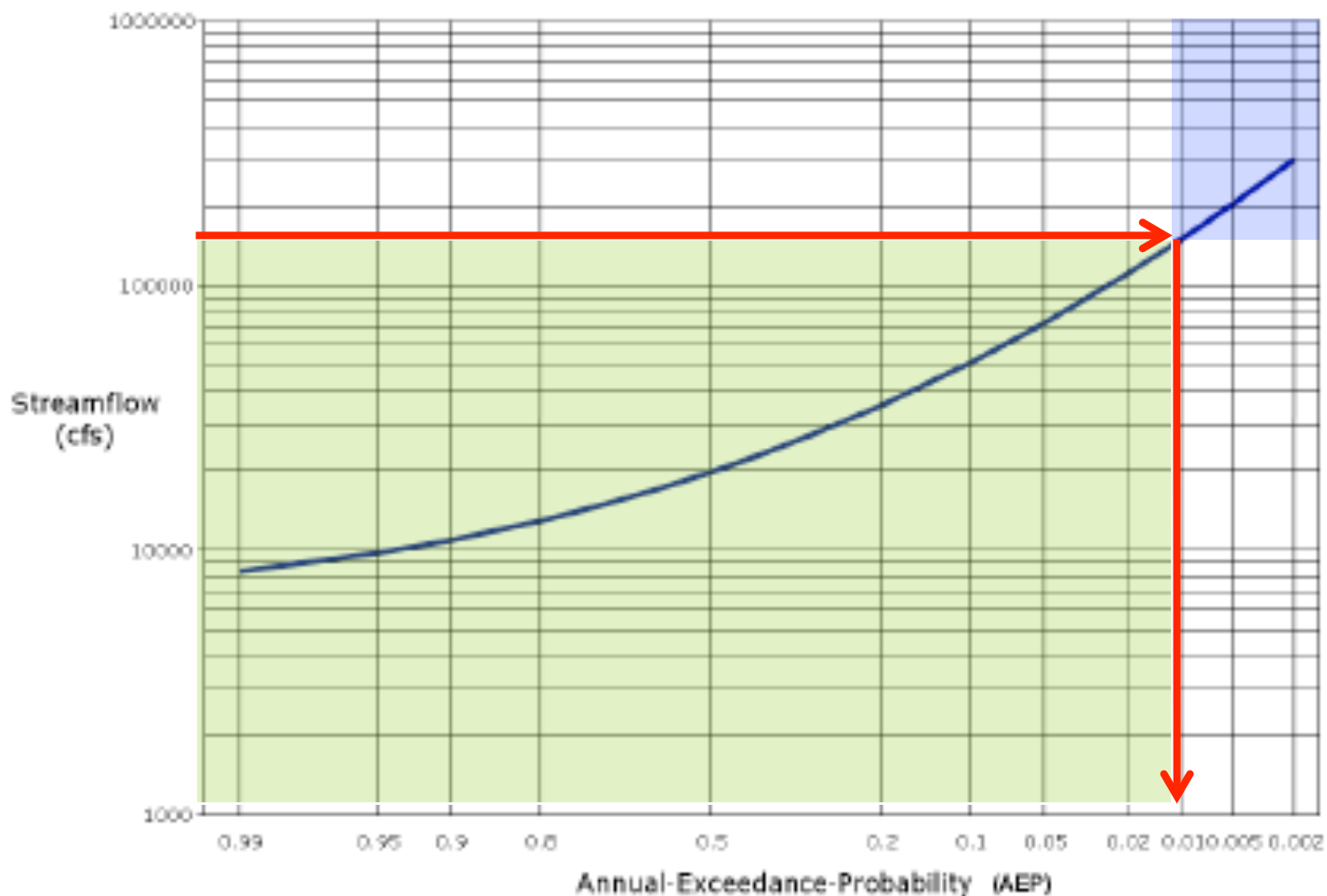
FLOOD FREQUENCY CURVE

- ▶ Probability of observing 20,000 cfs or greater in any year is 50% (0.5) (2-year).



FLOOD FREQUENCY CURVE

- ▶ Probability of observing 150,000 cfs or greater in any year is ??



PROBABILITY MODELS

- ▶ The probability in a single sampling interval is useful in its own sense, but we are often interested in the probability of occurrence (failure?) over many sampling periods.
- ▶ If the individual sampling interval events are independent, identically distributed then we satisfy the requirements of a Bernoulli process.

PROBABILITY MODELS

- ▶ As a simple example, assume the probability that we will observe a cumulative daily rainfall depth equal to or greater than that of Tropical Storm Allison is 0.10 (Ten percent).
- ▶ What is the chance we would observe one or more TS Allison's in a three-year sequence?

PROBABILITY MODELS

- ▶ For a small problem we can enumerate all possible outcomes.
 - ▶ There are eight configurations we need to consider:

	Year1	Year2	Year3	Probability
1	No TSA	No TSA	No TSA	$(.9)(.9)(.9)=0.729$
2	No TSA	No TSA	TSA	$(.9)(.9)(.1)=0.081$
3	No TSA	TSA	No TSA	$(.9)(.1)(.9)=0.081$
4	TSA	No TSA	No TSA	$(.1)(.9)(.9)=0.081$
5	No TSA	TSA	TSA	$(.9)(.1)(.1)=0.009$
6	TSA	TSA	No TSA	$(.1)(.1)(.9)=0.009$
7	TSA	No TSA	TSA	$(.1)(.9)(.1)=0.009$
8	TSA	TSA	TSA	$(.1)(.1)(.1)=0.001$

PROBABILITY MODELS

- ▶ So if we are concerned with one storm in the next three years the probability of that outcome is 0.243
 - ▶ outcomes 2,3,4; probabilities of mutually exclusive events add.
- ▶ The probability of three “good” years is 0.729.
- ▶ The probability of the “good” outcomes decreases as the number of sampling intervals are increased.

PROBABILITY MODELS

- ▶ The probability of the “good” outcomes decreases as the number of sampling intervals are increased.
 - ▶ So over the next 10 years, the chance of NO STORM is $(.9)^{10} = 0.348$.
 - ▶ Over the next 20 years, the chance of NO STORM is $(.9)^{20} = 0.121$.
 - ▶ Over the next 50 years, the chance of NO STORM is $(.9)^{50} = 0.005$ (almost assured a storm).

PROBABILITY MODELS

- ▶ To pick the chances of k storms in n sampling intervals we use the binomial distribution.

$$P[k - \text{events}, n - \text{samples}, p_T] = \frac{n!}{(n-k)!k!} p_T^k (1 - p_T)^{n-k}$$

- ▶ This distribution enumerates all outcomes **assuming unordered sampling without replacement**.
 - ▶ There are several other common kinds of counting:
 - ▶ ordered with replacement (order matters), samples are replaced
 - ▶ unordered with replacement
 - ▶ ordered without replacement

USING THE MODELS

- ▶ Once we have probabilities we can evaluate risk.
- ▶ Insurance companies use these principles to determine your premiums.
 - ▶ In the case of insurance one can usually estimate the dollar value of a payout – say one million dollars.
 - ▶ Then the actuary calculates the probability of actually having to make the payout in any single year, say 10%.
 - ▶ The product of the payout and the probability is called the expected loss.
 - ▶ The insurance company would then charge at least enough in premiums to cover their expected loss.

USING THE MODELS

- ▶ They then determine how many identical, independent risks they have to cover to make profit.
- ▶ The basic concept behind the flood insurance program, if enough people are in the risk base, the probability of all of them having a simultaneous loss is very small, so the losses can be covered plus some profit.
- ▶ If we use the above table (let the Years now represent different customers), the probability of having to make one or more payouts is 0.271.

USING THE MODELS


- ▶ If we use the above table, the probability of having to make one or more payouts is 0.271.

	Customer 1	Customer 2	Customer 3	Probability	<u>E(loss)</u>
1	No Loss	No Loss	No Loss	0.729	0
2	No Loss	No Loss	Loss	0.081	\$81,000
3	No Loss	Loss	No Loss	0.081	\$81,000
4	Loss	No Loss	No Loss	0.081	\$81,000
5	No Loss	Loss	Loss	0.009	\$9,000
6	Loss	Loss	No Loss	0.009	\$9,000
7	Loss	No Loss	Loss	0.009	\$9,000
8	Loss	Loss	Loss	0.001	\$1,000

USING THE MODELS

- ▶ So the insurance company's expected loss is \$271,000.
- ▶ If they charge each customer \$100,000 for a \$1 million dollar policy, they have a 70% chance of collecting \$29,000 for doing absolutely nothing.
 - ▶ Now there is a chance they will have to make three payouts, but it is small – and because insurance companies never lose, they would either charge enough premiums to assure they don't lose, increase the customer base, and/or misstate that actual risk.

DATA NEEDS FOR PROB. ESTIMATES

1. Long record of the variable of interest **at** location of interest
 2. Long record of the variable **near** the location of interest
 3. Short record of the variable **at** location of interest
 4. Short record of the variable **near** location of interest
 5. **No records near** location of interest
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ANALYSIS RESULTS

- ▶ Frequency analysis is used to produce estimates of
 - ▶ T-year discharges for regulatory or actual flood plain delineation.
 - ▶ T-year; 7-day discharges for water supply, waste load, and pollution severity determination. (Other averaging intervals are also used)
 - ▶ T-year depth-duration-frequency or intensity-duration-frequency for design storms (storms to be put into a rainfall-runoff model to estimate storm caused peak discharges, etc.).

ANALYSIS RESULTS

- ▶ Data are “fit” to a distribution; the distribution is then used to extrapolate behavior

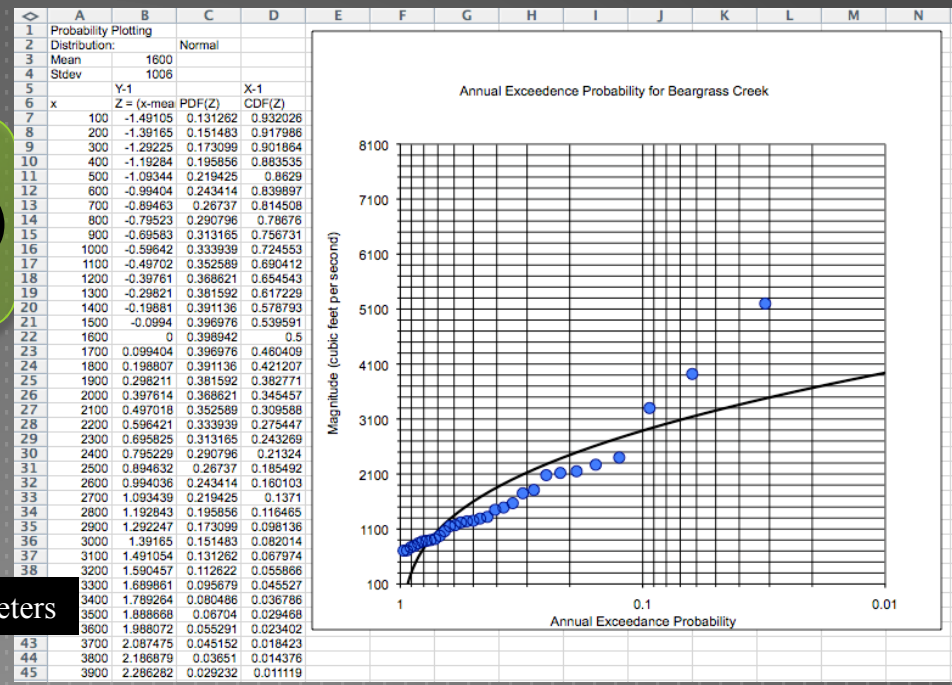
AEP

$$F(x) = \frac{1}{2} \left(1 + \operatorname{erf} \left(\frac{x - \mu}{2\sigma} \right) \right)$$

Magnitude

Error function
(like a key on a calculator
e.g. log(), ln(), etc.)

Distribution Parameters



DISTRIBUTIONS

$$pdf(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

Normal Density

$$cdf(x) = \int_{-\infty}^x \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(t-\mu)^2}{2\sigma^2}\right) dt = \frac{1}{2} \left(1 + erf\left(\frac{x-\mu}{\sigma\sqrt{2}}\right)\right)$$

Cumulative Normal Distribution

DISTRIBUTIONS

$$pdf(x) = \frac{\lambda}{\Gamma(n)} (\lambda x)^{n-1} \exp(-\lambda x)$$

Gamma Density

$$cdf(x) = \int_0^x \frac{\lambda}{\Gamma(n)} (\lambda t)^{n-1} \exp(-\lambda t) dt$$

Cumulative Gamma Distribution

DISTRIBUTIONS

$$pdf(x) = \frac{1}{\beta} \exp\left(\frac{-(x - \alpha)}{\beta} - \exp\left(\frac{-(x - \alpha)}{\beta}\right)\right)$$

Extreme Value (Gumbel) Density

$$cdf(x) = \exp\left(-\exp\left(\frac{-(x - \alpha)}{\beta}\right)\right)$$

Cumulative Gumbel Distribution

PLOTTING POSITIONS



PLOTTING POSITIONS

- ▶ A plotting position formula estimates the probability value associated with specific observations of a stochastic sample set, based solely on their respective positions within the ranked (ordered) sample set.

Bulletin 17B →

<u>Reference</u>	<u>a</u>	<u>Formula</u>
Weibull (1939)	0	$i / (n + 1)$
Blom (1958)	0.375	$(i - 0.375) / (n + 0.25)$
Cunnane (1978)	0.4	$(i - 0.4) / (n + 0.2)$
Gringorten (1963)	0.44	$(i - 0.44) / (n + 0.12)$
Hazen (1914)	0.5	$(i - 0.5) / n$

i is the rank number of an observation in the ordered set,
 n is the number of observations in the sample set

PLOTTING POSITION FORMULAS

- ▶ Values assigned by a plotting position formula are solely based on set size and observation position
 - ▶ The magnitude of the observation itself has no bearing on the position assigned it other than to generate its position in the sorted series (i.e. its rank)
- ▶ Weibull - In common use; Bulletin 17B
- ▶ Cunnane – General use
- ▶ Blom - Normal Distribution Optimal
- ▶ Gringorten - Gumbel Distribution Optimal

PLOTTING POSITION STEPS

1. Rank data from small to large magnitude.
 1. This ordering is non-exceedence
 2. reverse order is exceedence
2. compute the plotting position by selected formula.
 1. p is the “position” or relative frequency.
3. plot the observation on probability paper
 1. some graphics packages have probability scales

BEARGRASS CREEK EXAMPLE

- ▶ Examine concepts using annual peak discharge values for Beargrass Creek
- ▶ Data are on class server

NEXT TIME

- ▶ Probability estimation modeling (continued)
- ▶ Bulletin 17B